A Novel Integration of Three-Level AC–DC Converter with Closed Loop Controller

Mr V Jayanth Kumar¹

Dr O. Chandra Sekhar²

¹P.G Student, K.L University, Green fields, vaddeswaram, Guntur, Andhra Pradesh, India, jayanthfun4all@hotmail.com

²Professor, K.L University, Green fields, vaddeswaram, Guntur, Andhra Pradesh, India, sekhar.obbu@gmail.com

Abstract: In this project, closed loop integrated three-level ac–dc converter is presented in order to improve the stability of the system. By implementation of PI controller with PWM technique in closed loop, the switching sequence is under controlled condition and the output voltage of the proposed converter effectively increases. Mainly the present converter is combination of the operation of boost power factor correction and three-level dc–dc converter. Two large capacitors are taken in order to improve the efficiency and accuracy of the ac–dc converter. This converter operated with two different controllers. Power factor correction and regulation of dc bus voltage was done by input controller. The output voltage is maintained by output controller. In this we are using single stage converter topology in which the dc bus voltage in single stage converter is controlled by input controller. Finally in this project we are maintaining the stability of the previously implemented three-level integrated ac–dc converter. The flexibility of the improved converter is obtained from prototype which are shown in simulation results by using MATLAB/Simulink.

Index Terms: AC–DC power conversion, single-stage power factor correction (SSPFC), three-level converters.

I. INTRODUCTION

For running industrial dries power electronic dries are much essential. High power and medium voltage requirements, drives are implemented in recent period. Limited Voltage and current ratings of a semiconductor can be overwhelmed by the means of series or parallel connection of drives. Multi-level inverters have become popular because of their capability to obtain waveforms with less harmonic distortion and achieve higher voltages. Transformer isolation is needed for ac–dc power supplies which are developed with some kind of input Power factor correction to fulfil with standard of harmonics like IEC 1000-3-2.

Advancement is done in usage of power electronic converters which are manufactured in order to develop products with power factor correction. The essential requirement for performance of power electronic converters are high power factor and currents with low input harmonics. Old rectifiers with passive diode or LC filter with input can be combined to fit by using filters with passive elements. Because of the size of Inductors and capacitors of low frequency, the converter is very huge and heavy. In order to obtain better power factor and reduction of harmonics, Active power factor correction techniques have been used in AC–DC converter. Active power factor correction can be classified into two stage scheme. Two stages PFC contain two independent power stages in cascade with PFC stage and DC–DC regulator. The total efficiency of the two stages is lower because the total power has to be processed twice with two cascade power stage. Cost of the circuit is increase several schemes have developed to combine stage into one stage.

The open loop control of a three level integrated ac–dc has very less output voltage. To regulate the excessive dc bus voltages, minimize the large output ripples, distorted input currents and for better output voltage there is a need for a converter, which overcomes all these drawbacks.

In this paper, a closed loop control of a single stage three level integrated ac–dc converter that does not have the drawbacks of previously proposed single-stage and two-stage converters is proposed.
II. OPERATION OF THE PROPOSED CONVERTER

The implemented converter in open loop condition, as shown in Fig. 1, which mixes dc–dc converter three levelled fed by ac–dc boost Power Factor Correction converter. The ac–dc boost section consists of an input diode bridge, boost Inductor $L_{in}$, boost diode $D_{x1}$, and switch $S_4$, which is shared by the multilevel dc–dc section. Boost inductor cannot collect any energy when $S_4$ turn off. In this case, diode $D_{x2}$ prevents input current from flowing to the midpoint of capacitors $C_1$ and $C_2$ and diode $D_{x1}$ conducts and helps to transfer the energy stored in the boost inductor $L_{in}$ to the dc bus capacitor. Diode $D_{x3}$ bypasses $D_{x2}$ and makes a path for circulating current. It contains a single converter which can be monitored with two controllers independently. Power Factor correction and voltage regulation across the dc-bus capacitors on the primary side by giving specific triggering signal to $S_4$ can be achieved by one controller. The output voltage regulation by giving specific triggering signals to $S_1$ to $S_4$ can be done by other controller. The section of input can be monitored which is separated from the control of section of dc-dc and thereby individually designed. The output of input controller can be found by triggering signal of $S_1$ which is based on $S_4$, the generation of this signal can be discussed clearly in this project in coming section. When both switches are turn ON for half a switching cycle which are not at same time, then obtaining triggering signals for $S_2$ and $S_3$ are simple. In Fig.2 and Fig.3 the waveforms of converter and the diagrams of similar circuit which show the stages of operation of converter with the resultant bridge diode rectifier fed by sinusoidal source which is rectified as shown. The supply voltage is assumed and remained same only when the input line frequency is much lower than the switching frequency. Even though the input current is made discontinuous which is not desired but the input current can be made continuous. The different stages of operation of converter are given below.

1) Mode 1 ($t_0 \leq t \leq t_1$): During this mode, the output load is energized by the discharge of dc-bus capacitor $C_1$ by turn ON of switches $S_1$ and $S_2$. The positive voltage on the output side of transformer is given across $L_0$ which makes current rising.

2) Mode 2 ($t_1 \leq t \leq t_2$): During this mode, the output load is energized by the discharge of dc-bus capacitor $C_1$ by making $S_1$ and $S_2$ still turn ON and $S_3$ turns ON and also the output voltage of the diode bridge rectifier is given across the input inductor $L_{in}$ thereby inductor current rising.

3) Mode 3 ($t_2 \leq t \leq t_3$): In this mode, the switches $S_1$ and $S_2$ are still turn ON and $S_3$ turns ON. The output load is energized by discharging of dc-bus capacitor $C_1$. The output voltage of diode bridge rectifier is applied across input inductor $L_{in}$ in order to make the current rising.
the inductor current which raises voltage applied across input inductor $L_{in}$ thereby inductor current rising.

$V_{pri}$

$V_{g1}$

$V_{g2}$

$V_{g3}$

$V_{g4}$

$i_{Lin}$

$i_{Lo}$

$i_{in}$

$D_1T_s$ $D_2T_s$ $D_3T_s$

Fig. 2. Typical waveforms describing the modes of operation.

4) Mode 4 ($t_3 \leq t \leq t_4$): During this mode, the switches $S_1$ and $S_2$ are turn OFF and $S_4$ is turn ON such that the capacitor $C_2$ is charged by the primary current of the transformer through the body diode of switch $S_3$ and diode $D_{3x}$. 

5) Mode 5 ($t_4 \leq t \leq t_5$): In this mode, $S_1$ and $S_4$ are ON. Energy flows from capacitor $C_2$ flows into the load while the current flowing through input inductor $L_{in}$ continues to rise.

6) Mode 6 ($t_5 \leq t \leq t_6$): In this mode, $S_4$ turns off. The current in input inductor flows thorough the diode $D_{3x}$ to charge the capacitors $C_1$ and $C_2$. The current in the transformer primary flows thorough the $S_3$ and $D_2$. This mode ends when the inductor current reaches zero. Also during this mode, the load inductor current freewheels in the secondary of the transformer.

7) Mode 7 ($t_6 \leq t \leq t_7$): In this mode, the load inductor current freewheels in the secondary of the transformer. This mode ends when the switches $S_4$ turns off.
8) Mode 8 (t7 ≤ t ≤ t8): In this mode, S3 is OFF and the current in the primary of the transformer charges capacitor C1 through the body diodes of S1 and S2. Finally, converter reenters Mode 1.

III. CONTROL STRATEGY AND CONVERTER DESIGN

This section mainly focused on the control technique for the Single stage three level controllers. Closed loop PI controller with PWM technique gives the better performance as compared with the conventional converter. The block diagram of the proposed control technique is shown in Fig 3.

PI controller receives output voltage as input signal. Based on the input signal the PI controller generates a reference dc voltage signal which is an input signal to PWM generator. The values of PI controller gains (i.e. Integral gain and proportional gain) are tuned in order to attain better output voltage. The PWM generator compares the dc reference signal with the saw tooth carrier signal and generates the pulses.

A procedure for the design of the converter is presented in this section and is demonstrated with an example. The converter is to be designed with the following parameters for the example:
1) input voltage: \( V_{in} = 90 \text{ to } 265 \text{ Vrms} \);
2) output voltage: \( V_o = 48 \text{ V} \);
3) maximum output power: \( P_o = 1350 \text{ W} \);
4) switching frequency: \( f_{sw} = 1/T_{SW} = 50 \text{ kHz} \);
5) input current harmonics: IEC1000-3-2 for Class D electrical equipment.

A. Step 1: Determine Value for Output Inductor \( L_o \)

The output inductor should be designed so that the output current is made to be continuous under most operating conditions. The minimum value of \( L_o \) should be the value of \( L_o \) with which the converter’s output current will be continuous on the when the converter is operating with maximum input voltage, minimum duty cycle (\( D_m \)), and at least 50% of maximum load. The minimum value of \( L_o \) can, therefore, be determined to be

\[
L_o, \text{min} \geq \frac{V_o}{I_o, \text{max}} \left( \frac{1}{1-D_m T_{SW}} \right)
\]

Substituting \( P_o, \text{max} = 1350 \text{ W}, V_o = 48 \text{ V}, T_{SW} = 20 \mu s, \text{ and } D_m = 0.45 \) gives \( L_o, \text{min} \geq 9.36 \mu H \) and the value of \( L_o \) should be larger to provide some margin. It should be noted that such a value is considerably higher than what is typically found in most other single-stage full-bridge converters, which must operate with very low output inductor values to prevent the dc-bus voltage from becoming excessive. A value of \( L_o = 10 \mu H \), which is just above 9.36 \mu H, is chosen.
B. Step 2: Determine Value for Turns Ratio of Main Transformer N

The relation between $V_{bus}, D, V_o$ and $N$ is

$$V_D = \frac{V_{bus} \cdot D}{2N} \quad (2)$$

The minimum value of $N$ can be found by considering the case when the converter must operate with minimum input line and, thus, minimum primary-side dc-bus voltage $V_{bus, min}$ and maximum duty cycle $D_{max}$.

$$N \geq \frac{V_{bus, min}}{2V_o \cdot D_{max}} \quad (3)$$

$V_{bus} = 650$ V and it is achieved by controlling the $S4$. Substituting $V_o = 48$ and $D_{max} = 0.75$, then the value of $N$ should be equal or more than 5. In this example, the value of transformer ratio is considered to be equal to $N = 5$.

C. Step 3: Determine Value for Inductor $L_{in}$

The value for $L_{in}$ should be low enough to ensure that the input current is fully discontinuous under all operating conditions, but not so low as to result in excessively high peak current. For the case where $L_{in}$ is such that the input current remains discontinuous for all operating conditions, the minimum value of $L_{in}$ determine as

$$L_{in, max} < \left(\frac{\left(V_{bus, min}\right)^2 \cdot D_{max} \cdot (1 - D_{max})^2}{2P_o, max / f_{SW}}\right) \quad (4)$$

Where $D_{max} = 0.75$, $V_{bus, min} = 650$ V, $P_o, max = 1.35$ kW, and $f_{SW} = 50$ kHz. The minimum value of $L_{in} = 114$ $\mu$H is found. For this design, $L_{in} = 80$ $\mu$H is used. One controller is used to control dc-bus voltage and shape the input current and one controller for control output voltage. The time constant for PFC controller should be faster in compare to output voltage controller.

IV. CONVERTER FEATURES

The proposed converter has the following features:

A. Reduced cost compared to two-stage converters:

Although the proposed converter may seem expensive, the reality is that it can be cheaper than a conventional two-stage converter. This is because replacing a switch and its associated gate drive circuitry with four diodes reduces cost considerably even though the component count seems to be increased—this is especially true if the diodes are ordered in bulk numbers.

B. Better performance than a single-stage converter:

The proposed single-stage converter can operate with a better input power factor for universal input line applications than a single-controller, single-stage because it does have a dedicated controller for its input section that can perform PFC and regulate the dc-bus voltage. The presence of a second controller also allows the converter to operate with better efficiency and with less output ripple as each section.

C. Improved Light-Load Efficiency:

The proposed converter can be designed so that it has a conventional dc-bus voltage of 400 V. Since the converter is a multilevel converter, a 400 V dc bus means that each switch will be exposed to a maximum voltage of 200 V. Having 200 V across a MOSFET device instead of 400 V (as is the case with two-level converters) results in a 75% reduction in turn on losses when the converter is operating under light-load conditions and there is an insufficient amount to current available to discharge the switch output capacitances before the switches are turned on.

D. Increased Design Flexibility:

Since the converter is a multilevel converter, it can be operated with high dc-bus voltage (800 V), standard dc-bus voltage (400 V), or any dc-bus voltage 400 V < $V_{bus}$ < 800 V. There are advantages to operating with high dc-bus voltage or with standard dc bus voltage. The fact there is flexibility in the level that the dc-bus voltage is set means that there is considerable flexibility in the design of the converter. This gives the designer options as to how to optimize the design of the converter for other factors such as efficiency profile and cost (i.e. cost of switches based on voltage rating considerations and availability). It should be noted that this design flexibility makes the design of the three-level converter to be much simpler than that of a single-stage two-level converter or that of a single-
controller three-level single stage converter as the
dc-bus voltage can be fixed to a desired level that is
considered appropriate. It should be noted that
although the proposed converter has the
aforementioned advantages over the conventional
two-stage converter, it will have lower heavy-load
efficiency because of increased conduction losses as
switch S4 must conduct both the input current and
the full-bridge current. As a result, when
determining whether to use the proposed converter
versus a conventional two-stage converter, the main
trade off that needs to be considered is lower cost
and improved light-load efficiency versus heavy-
load efficiency.

V. MATLAB/SIMULINK RESULTS

Case i: Single-Stage Three-Level Converter Under
open loop condition.

Fig.4: Matlab/Simulink circuit of Single-Stage
Three-Level Converter in open loop condition.

Fig.5: Input Current and Voltage Wave Forms

Fig.6: Voltage across Switch S1

Fig.7: Voltage across Switch S2

Fig.8: Voltage across Switch S3

Fig.9: Voltage across Switch S4
VI. CONCLUSION

A closed loop control of a three level integrated ac–dc converter is proposed in the paper. This converter is operated with two controllers, one controller that performs input PFC and a second controller that regulates the output voltage. The outstanding feature of this converter is that it combines the performance of two-stage converters with the reduction of cost of single-stage converters. By using PI controller with PWM technique in closed loop, the switching sequence is under controlled condition. Hence the proposed converter output dc voltage is effectively increased. Efficiency of the proposed converter is also comparatively more. For high dc voltage requirements this proposed converter is efficient.

The paper introduces the proposed converter, explains its basic operating principles and modes of operation, and discusses its design with respect to different dc-bus voltages.
REFERENCES


