Investigation of High Frequency Lossless Step-up DC-DC Switching Converter Employing Electronic PI-Controller

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Abstract— In this paper, a high frequency Soft-switching Step-up DC-DC converter is proposed with a trouble-free auxiliary resonant circuit, which is composed of an auxiliary switch, a diode, a resonant inductor, and a resonant capacitor. The conventional Step-up converter decreases the efficiency because of Hard-switching, which generates losses when the switches are turned ON/OFF. During this interval, all switches in the adopted circuit perform Zero-Current Switching (ZCS) by the resonant inductor at turn-ON, and Zero-Voltage Switching (ZVS) by the resonant capacitor at turn-OFF. This switching pattern can reduce the switching losses, voltage and current stress of the switching device. In this work, we have analysed the operational modes of the adopted Soft-switching Step-up converter with closed-loop control mode using Electronic PI-controller. The adopted Soft-switching Step-up converter is simulated by PowerSIM (PSIM) software. The results obtained are presented to verify the effectiveness of the proposed circuit.

Keywords— Soft-switching, ZCS, ZVS, Step-up Converter, Electronic PI-controller.

1. Introduction

Recently, switch-mode power supplies has become smaller and lighter, because the switching frequency has increased. However, as the switching frequency has increased, the periodic losses at turn-ON/OFF have also increased. As a result, this loss brings increasing loss of whole system. Therefore, to reduce these switching losses, a soft-switching method is proposed, which involves an added auxiliary circuit, instead of a conventional hard-switching converter. However, the auxiliary circuit for resonance increases the complexity and cost. For some resonant converter with auxiliary switch, main switch achieves soft-switching but auxiliary switch performs hard switching. Thus, these converters cannot improve the whole system efficiency owing to switching loss of auxiliary switch. On the other hand, in cases of converters doing hard switching at a high frequency, the switching loss increases in proportion to the switching frequency. Thus, in order to reduce switching losses, the soft switching technology, which uses resonance by inductor and capacitor, has been actively researched [1-5].

The proposed converter has better efficiency than a conventional Step-up converter. Through this circuit, all of the switching devices perform soft-switching under zero-voltage and zero-current conditions. Therefore, the periodic losses generated at turn-ON and turn-OFF can be decreased. The adopted soft-switching Step-up DC-DC converter is simulated by PowerSIM (PSIM) software.

2. Proposed Soft Switching Step-up DC-DC Converter

The auxiliary circuit is composed of main switch (S1), an auxiliary switch (S2), a resonant capacitor (C), a resonant inductor (L), and two diodes (D1 and D2), as shown in Fig.1. The operational principle of this converter can be divided into six intervals.

Fig.1: Proposed Step-up DC-DC Converter.
2.1 Interval-1 \((t_0 \leq t < t_1)\)

Switches \(S_1\) and \(S_2\) are both in the OFF state, the current cannot flow through switches \(S_1\) and \(S_2\), and the accumulated energy of the main inductor is transferred to the load. In this interval, the main inductor current decreases linearly. During this time, the current does not flow to the resonant inductor, and the resonant capacitor has charged as output voltage.

After two of the switches have been turned-ON, interval-1 is over. These conditions are as follows:

\[
v_L(t) = V_S - V_o \quad (1)
\]

\[
i_L(t) = i_L(t_0) - \frac{V_o - V_S}{L_i} t \quad (2)
\]

\[
i_{L_1}(t) = i_L(t) \quad (3)
\]

\[
i_{L_2}(t) = 0 \quad (4)
\]

\[
v_{C_r}(t) = V_o \quad (5)
\]

2.2 Interval-2 \((t_1 \leq t < t_2)\)

After turning on switches \(S_1\) and \(S_2\), the current flows to the resonant inductor. At that time, two of the switches are turned-ON under zero-current condition. This is known as Zero-Current Switching (ZCS). Because the main and auxiliary switches implement ZCS, this converter has lower switch loss than the conventional hard switching converter. As the resonant current rises linearly, the load current gradually decreases. At \(t_2\), the main inductor current equals the resonant inductor current, and the output diode current is zero. When the resonant capacitor voltage equals \(V_o\), the output diode is turned-off, and interval-2 is over.

\[
i_{L_2}(t_1) = 0 \quad (6)
\]

\[
v_{L_2}(t) = V_o \quad (7)
\]

\[
i_{L_1}(t) = \frac{V_o}{L_r} t \quad (8)
\]

\[
i_L(t) = i_{L_2}(t_2) \quad (9)
\]

\[
i_{L_1}(t_2) = 0 \quad (10)
\]

2.3 Interval-3 \((t_2 \leq t < t_3)\)

The current that flowed to the load through output diode \(D_o\) no longer flows, since \(t_2\) and the resonant capacitor \(C_r\), and the resonant inductor \(L_r\) start a resonance. The current flowing to the resonant inductor is a combination of the main inductor current and the resonant capacitor current.

\[
i_L(t) \equiv I_{min} \quad (11)
\]

During this resonant period, the resonant capacitor \(C_r\) is discharged from \(V_o\) to zero. Resonant frequency and impedance are given by equations (14) and (15). When the voltage of the resonant capacitor equals zero, the interval-3 is over.

\[
v_{C_r}(t_2) = V_o \quad (12)
\]

\[
v_{C_r}(t_3) = 0 \quad (13)
\]

\[
\omega_r = \frac{1}{\sqrt{L_r C_r}} \quad (14)
\]

\[
Z_r = \frac{L_r}{\sqrt{C_r}} \quad (15)
\]

2.4 Interval-4 \((t_3 \leq t < t_4)\)

After the resonant period in interval-3, when the voltage of the resonant capacitor equals zero, interval-4 begins. In this interval, the freewheeling diodes of \(D_1\) and \(D_2\) are turned-ON, and the current of the resonant inductor is the maximum value. The resonant inductor current flows to the freewheeling diodes \(S_1-L_r-D_2\) and \(S_2-L_r-D_1\) along the freewheeling path.

\[
i_L(t) = i_{L_2}(t) + i_{D_1}(t) + i_{D_2}(t) \quad (16)
\]

\[
i_L(t_3) = i_{L_2}(t_4) = I_{L_2,max} \quad (17)
\]

During this time, the main inductor voltage equals the input voltage, and the current accumulating energy increases linearly.
\[ v_L(t) = V_s \]  
\[ i_L(t) = I_{\text{min}} + \frac{V_s}{L} t \]  

\[ 2.5 \text{ Interval- } 5 \quad (t_4 \leq t < t_5) \]

In interval-5, all of switches are turned-OFF under the zero voltage condition by the resonant capacitor. During this interval, the initial conditions of the resonant inductor current and resonant capacitor voltage are as follows:

\[ i_{L_4}(t_4) = i_{L,\text{max}} \]  
\[ v_{C_4}(t_4) = 0 \]

When all of the switches are turned-OFF, the resonant capacitor \( C_r \) is charged to the output voltage by two of the inductor currents. Until the resonant capacitor has been charged to \( V_o \), the output diode is in the OFF state.

\[ i_L(t) \simeq I_{\text{max}} \]  
\[ v_{C_4}(t_5) = V_o \]  

\[ 2.6 \text{ Interval-6} \quad (t_5 \leq t < t_6) \]

Interval-6 begins when the resonant capacitor equals the output voltage, and the output diode is turned-ON under the zero voltage condition. During this interval, the main inductor current \( i_L \) and the resonant inductor current \( i_{L_r} \) flow to the output through the output diode \( D_o \).

\[ i_{D_6}(t) = i_{L}(t) + i_{L_r}(t) \]  
\[ v_{C_6}(t) = V_o \]

At that time, two of the inductor currents are linearly decreased, and the energy of the resonant inductor is completely transferred to the load. Then, the interval-6 is over.

\[ i_L(t) = I_{\text{max}} - \frac{V_o - V_s}{L} t \]  
\[ i_{L_r}(t) = i_{L_4}(t_6) - \frac{V_o}{L_r} t \]

\[ i_{L_4}(t_5) = 0 \]  

\[ 3. \text{ Design Procedure of Resonant Inductor and Capacitor} \]

To satisfy the Zero-Voltage Switching (ZVS) condition, the resonant inductor current must exceed the main inductor current during the freewheeling interval of interval-4.

In Fig. 2, the time of interval-2, which is the rising time of the resonant inductor current, is expressed by equation (29). For the maximum resonant current, the time of interval-3, which is the resonant time of the resonant inductor and capacitor, is defined as one-fourth of the resonant period. As a rule of thumb, the rising time of the resonant inductor current (intervals 2–3) can be set to 10% of the minimum ON time. This is expressed as in equation (31).

\[ t_2 - t_1 = \frac{L}{V_o} I_{\text{min}} \]  
\[ t_3 - t_2 = \frac{T}{4} \]  

\[ \frac{L}{V_o} I_{\text{min}} + \frac{T}{4} = 0.1DT \]  

\[ \frac{V_o}{Z_r} > \Delta i_L \]
Table-1: Step-Up Converter Specifications

<table>
<thead>
<tr>
<th>Input Voltage</th>
<th>V_{in}</th>
<th>200 V</th>
</tr>
</thead>
<tbody>
<tr>
<td>Switching Frequency</td>
<td>F</td>
<td>30 KHz</td>
</tr>
<tr>
<td>Main Inductor</td>
<td>L</td>
<td>560 mH</td>
</tr>
<tr>
<td>Resonant Inductor</td>
<td>L_r</td>
<td>40 µH</td>
</tr>
<tr>
<td>Resonant Capacitor</td>
<td>C_r</td>
<td>20 nF</td>
</tr>
<tr>
<td>Output Capacitor</td>
<td>C_o</td>
<td>1000 µF</td>
</tr>
</tbody>
</table>

4. Simulation Results

4.1 Open-Loop Circuit Of Proposed Step-up Converter

The adopted Soft-switching Step-up Converter for input voltage of 200V and switching frequency of 30KHz is simulated using the PSIM software. The Fig.3 shows the simulated waveforms of main switch voltage and current in open-loop. Under resonance condition, the resonant inductor and capacitor, ZCS and ZVS are achieved at turn-ON and turn-OFF.

4.2 Closed-Loop Circuit Of Proposed Step-up Converter

Electronic PI-controller with the use of op-amps is adopted here to control the output voltage for any change in the input voltage and the corresponding reference voltage. The Fig.5 shows the schematic diagram of the closed-loop control for the proposed Step-up converter.

Fig.2: Simulated waveforms of main switch voltage and current in open-loop.

Fig.4: Simulated waveforms of the gate pulse and main inductor current in open-loop.

Fig.5: Closed-loop circuit of proposed Step-up converter in PSIM.

switch is turned-ON, the energy of inductor is accumulated. When it is turned-OFF, this energy is transferred to the output.
The Proportional gain (\(K_P\)) and the Integral gain (\(K_I\)) are calculated by using equations (33) and (34).

\[
K_P = \frac{R_2}{R_1} \quad (33)
\]

\[
K_I = \frac{1}{R_2C} \quad (34)
\]

The Fig. 6 shows the simulated waveforms of main switch voltage and current in closed-loop of step-up converter.

Fig. 3: Simulated waveforms of main switch voltage and current in closed-loop.

4.3 Comparison between Open-Loop and Closed-Loop Response

For the input voltage of 200 V and switching frequency of 30 KHz, the output voltage is compared with open-loop and closed-loop. From the simulated waveform of output voltage in open-loop as shown in Fig.7 and simulated waveform of output voltage in closed-loop as shown in Fig.8, it is clearly noticed that the closed-loop has greatly improved the voltage profile, when compared with open-loop.

Fig. 7: Simulated waveform of output voltage in open-loop.

Fig. 8: Simulated waveform of output voltage in closed-loop.
The switching devices used in this step-up converter have achieved ZCS and ZVS conditions by the resonant inductor and capacitor at turn-ON/OFF. Moreover the voltage stress across the hard switch and soft switch has been analysed and it is observed that the voltage stress in soft switching has been reduced when compared to the hard switching for various load conditions. The Fig. 9 shows that voltage stress across the switch under various load conditions.

5. Conclusion

In this proposed work, we have designed and analysed the operational modes of the adopted high frequency Soft-switching Step-up DC-DC Converter, which involved an added trouble-free auxiliary resonant circuit in the conventional Step-up converter with closed-loop control mode using Electronic PI-controller. This soft-switching Step-up converter is easy to control because the two switches are controlled by the same gating signal. Moreover all the switching devices in this converter have achieved ZCS and ZVS conditions by the resonant inductor and capacitor at turn-ON/OFF. As a result, the switching losses were reduced significantly.

References


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