FLOODING AND DRYING DIAGNOSIS OF PROTON EXCHANGE MEMBRANE FUEL CELLS USING ELECTROCHEMICAL IMPEDANCE SPECTROSCOPY ANALYSIS

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Abstract: Electrochemical impedance spectroscopy EIS is an experimental technique that can be used for measured the ac impedance spectra of polymer electrolyte fuel cell (PEMFC) cathodes under various experimental conditions. This ac impedance is used for identify electrode/flow channel flooding and membrane drying. The main goal of this work was to develop a suitable PEMFC impedance model, which can be using for used for diagnosis of PEM fuel cell. For this one a novel optimization method based on factorial Design methodology is used. It was applied for parametric analysis of electrochemical impedance Thus it is possible to evaluate the relative importance of each parameter to the simulation accuracy. Furthermore this work presents an analysis of the PEMFC impedance behavior in the case of flooding and drying.

Key words: PEMFC fuel cell; Electrochemical Impedance Spectroscopy (EIS); Water management; Design of Experimental (DoE); Fractional factorial design.

1. Introduction.
In recent years, with the problems of energy shortage and environment concerns, renewable and clean energy become more and more popular, one of the alternative sources of electric power is fuel cell. It is the clean energy, without any harmful emissions to the environment, and has high power density. Proton Exchange Membrane (PEM) fuel cell is one kind of fuel cells that can work in a comparatively high efficiency and low temperature condition. It is one of the promising technologies for alternative power source of residential power generation in future [1]-[5].

A PEMFC converts the chemical energy of a fuel, just as the hydrogen H₂, and an oxydizer, just as the oxygen O₂, in electrical energy. The outline of a typical PEMFC is illustrated in Fig. 1 [2]. On one side of the cell, referred to as the anode, the fuel is supplied under certain pressure. The fuel for this model is the pure gas H₂, although other compositions of gases can be used.

In these cases, the hydrogen concentration should be determined in the mixture. The fuel spreads through the electrode until it reaches the catalytic layer of the anode where it reacts to form protons and electrons, as shown below in the reaction given in Eq. (1) [1]-[5]:

$$H_2 + 1/2 O_2 \rightarrow H_2O + \text{heat} + \text{electrical energy}$$  \hspace{1cm} (1)

In order to get an electric current out of this reaction, hydrogen oxidation and oxygen reduction are separated by a membrane, which is conducting protons from the anode to the cathode side. The semi reactions on both electrodes are:

$$H_2 \rightarrow 2H^+ + 2e^- \quad \text{anode}$$  \hspace{1cm} (2)

$$O_2 + 4 e^- \rightarrow 2O_2^- \quad \text{cathode}$$  \hspace{1cm} (3)

While the protons are transported through the membrane, electrons are carried by an electric circuit in which their energy can be used. This process is shown in fig 1.

Protons are able to cross the membrane only if attached to water molecules. Thus, it is of prime importance to ensure at all time steady minimum water content in the electrolyte. Water management is one of the most critical elements of PEM fuel cell design [6].

It can enter the PEMFC via the anode and cathode gas streams and is produced at the cathode by the oxygen.
reduction. It exits the PEMFC via evaporation, primarily at the cathode. In main order this paper outlines the processing and results of algorithm development for fuel cell diagnostics using electrochemical impedance spectroscopy (EIS) data [6]-[8]. This has been done to assist with the development of both onboard and off-board fuel cell diagnostic hardware. Impedance can identify faults that cannot be identified solely by a drop in cell voltage. Furthermore, it is able to conclusively identify electrode/flow channel flooding and membrane drying.

2. Impedance Fuel cell model formulation

When there is no mass transport limitation, the redox reaction is simply represented by an equivalent electrical circuit of parallel RC cells. However, when there are considerable variations of the interfacial concentrations on electrodes, the Randles cell [6], is a common and practical way of modeling an electrochemical cell as an equivalent circuit. It consists of four elements: two resistors, \( R_m \), standing for the ohmic resistance of the electrolyte, here the proton exchange membrane, and \( R_p \) standing for the polarisation resistance, due to the oxygen reduction reaction; a plane capacitor, \( C_{dl} \), representing the double layer capacitance at the electrode/electrolyte interface; and the impedance of diffusion called Warburg impedance. It was modeled by the equation

\[
Z_W(j\omega) = \frac{RT}{n^2F^2S\sqrt{j\omega C_d D}} \tanh\left(\frac{\omega \delta^2}{C_d \sqrt{D}}\right) \tag{4}
\]

Where:
- \( \delta \): Diffusion layer width (m)
- \( D \): is the diffusion coefficient (m\(^2\) s\(^{-1}\))
- \( N \): number of electrons
- \( R \): perfect gas constant (J mol\(^{-1}\) K\(^{-1}\))
- \( F \): Faraday constant (A s mol\(^{-1}\))
- \( C_o \): oxygen concentration in cathode active layer (mol m\(^{-3}\))
- \( S \): active area (m\(^2\))
- \( T \): temperature (K)

Relation (1) can be re-written as:

\[
Z_W(j\omega) = \frac{RT}{n^2F^2S\sqrt{j\omega C_d D}} \frac{1}{C_d \sqrt{D}} \delta \frac{1}{\tanh\left(\frac{\omega \delta^2}{C_d \sqrt{D}}\right)} \tag{5}
\]

Which leads to the definition of two parameters, a time constant \( \tau_d \)

\[
\tau_d = \frac{S^2}{D} \tag{6}
\]

and a resistance, \( R_d \)

\[
R_d = \frac{RT}{n^2F^2S\sqrt{j\omega C_d D}} \frac{1}{C_d} \delta \tag{7}
\]

This leads to the final expression of the concentration–diffusion impedance:

\[
Z_w(j\omega) = R_d \tan\left(\frac{(\tau_d,j\omega)}{\sqrt{(\tau_d,j\omega)}}\right) \tag{8}
\]

Where

\( R_d \) is dimensionally homogenous to an electrical resistance and \( \tau_d \) is dimensionally homogenous to a time (s)

Finally, the total impedance of the fuel cell is composed of two impedances, one impedance for each electrode (anode and cathode), in series with the internal resistance \( R_m \) linked to the membrane. By further making the assumption that the rate limiting reaction is the oxygen reduction at the cathode, we will neglect the contribution of the anode impedance to the cell impedance. Thus, the equivalent circuit retained to model our fuel cell is that of Fig. 2, and the overall impedance is:

\[
Z(j\omega) = R_m + \frac{1}{j\omega C_d + (1/(R_p + Z_w))} \tag{9}
\]

Fig.2 Randles cell

As seen in Fig.3, the fitting of a Randles cell to the experimental data is good but not entirely satisfactory. The bulk of the problem comes from the high-frequency part of the model, for which the Randles cell predicts a semicircle centred on the \( x \)-axis, while experimental data clearly show a depressed semicircle (i.e. centered below the \( x \)-axis). As a side-effect, the model misplaces the transition between the two semicircles. These depressed semicircles are usually dealt with by changing the standard plane capacitor of the Randles circuit into a constant phase element (CPE), as seen in Fig.3. Whereas the standard plane capacitor exhibits a first-order behavior, the CPE impedance is defined by:
With a value of $\alpha$ usually ranging between 0.5 and 1. Thus, the impedance of the equivalent circuit is now:

$$Z(j\omega) = Z_{cpe} + \frac{1}{Q(j\omega)^{\alpha} + (1/(R_p + Z_w))}$$

(11)

For identification of model parameters the non-linear least square fitting algorithm of MATLAB® was used to identify the relevant parameters of Randles cell developed in Section 2. The principle of this algorithm is to minimize the square of a nonlinear function while finding the best values of the unknown Variable (i.e. model parameters) starting from their given initial values.

It should be noted that the impedance points measured at low frequencies, whose physical significance is not clear, and the points of impedance having a positive imaginary part (due to wiring inductance) are not taken into account for this identification process. As shown in Section 2, the parameters of the fractional model, which are to be identified, are $R_m$ determined by an algorithm of identification and then this value is used to do “fitting” for the other parameters of the model with experimental results. The value of the time constant $\tau_d$ is calculated from the frequency corresponding to the peak of the diffusion arc. As far as internal resistance $R_m$ is concerned, it corresponds to the distance between the origin and the intersection of the impedance spectrum with the real axis.

The remaining parameters ($R_d$, $R_p$ and $Q$) are identified by using non-linear least square algorithm.

Table 1 shows the values of the model parameters identified for four impedance spectra Corresponding to flooding (RH=100%) and drying (RH=15%) by slightly reducing the space between lines.

3. Factorial Design of Experiments Methodology

A Design of Experiment (DoE) is a structured, organized method for determining the relationship between a number of factors affecting a process and the output of that process. Regardless of the domain of application, this methodology is useful for three objectives: screening, optimization, and robustness testing. Employed at the beginning of the investigation of a new application, screening experiments are commonly designed to explore many factors, in order to evaluate their effects on the responses. It also makes it possible to obtain the best possible precision on the modeling of results and thereafter the optimization of the process.

Definition of variation intervals of the factors

In this study the Factorial Design methodology can be used to evaluate the respective impacts of the relative humidity RH (%) and Time t(s) on the FC impedance operation. The full factorial design required $2^k + n$ experiments, where k is the number of factors [9]-[11]. The number of factors considered in our work are relative humidity RH (%) and Time t(s) the number of runs are 4 Table (2).

We use a full factorial design with 2 factors [9]. With such models, the response of the process is expressed their according to the factors $u_i$ ($i = 1,..., e$):

$$y = f (u_i) = c_0 + \sum_{i=1}^{e} c_i u_i + \sum_{i<j}^{e} c_{ij} u_i u_j$$

(12)

Table 1

<table>
<thead>
<tr>
<th>Time(s)</th>
<th>RH(%)</th>
<th>$R_m$</th>
<th>$Q$</th>
<th>$R_p$</th>
<th>$Rd$</th>
<th>$t_d$</th>
<th>$U$</th>
</tr>
</thead>
<tbody>
<tr>
<td>500</td>
<td>15</td>
<td>0.00512</td>
<td>0.952</td>
<td>0.0099</td>
<td>0.0051</td>
<td>0.1155</td>
<td>4.06</td>
</tr>
<tr>
<td>3700</td>
<td>15</td>
<td>0.0088</td>
<td>0.62</td>
<td>0.013</td>
<td>0.0101</td>
<td>0.1835</td>
<td>3.35</td>
</tr>
<tr>
<td>500</td>
<td>100</td>
<td>0.00398</td>
<td>1.109</td>
<td>0.008</td>
<td>0.0034</td>
<td>0.0872</td>
<td>4.18</td>
</tr>
<tr>
<td>3700</td>
<td>100</td>
<td>0.00416</td>
<td>0.936</td>
<td>0.0163</td>
<td>0.0312</td>
<td>0.0947</td>
<td>3.3</td>
</tr>
</tbody>
</table>
Where \( c_0, c_i, \) and \( c_{ij} \) are calculated coefficients. A normalized centered value can be defined for each factor as follows:

\[
x_i = \frac{(u_i - u_{ic})}{\Delta u_i} = u_i^*\tag{13}
\]

Where:

\[
u_{ic} = \frac{(u_{i}^{\max} + u_{i}^{\min})}{2}, \quad \Delta u_i = \frac{(u_{i}^{\max} - u_{i}^{\min})}{2} \tag{14}
\]

With these notations, the function of response becomes:

\[
y = f(x_i) = a_0 + \sum_{i=1}^{n} a_i x_i + \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij} x_i x_j\tag{15}
\]

Where \( x_i \) can obviously take only the values: \(-1\) (for minimal input value \( x_{i}^{\min} \)), \(+1\) (for maximal input value \( x_{i}^{\max} \)).

In the present study, i.e. \( x_1 = t^*(s), x_2 = RH^* \), the linear model of impedance will take the following form:

\[
R_m = a_0^t + a_1^t t^* + a_2^t RH^* + a_3^t t^* RH^*\tag{16}
\]

\[
Q = a_0^q + a_1^q t^* + a_2^q RH^* + a_3^q t^* RH^*\tag{17}
\]

\[
R_p = a_0^p + a_1^p t^* + a_2^p RH^* + a_3^p t^* RH^*\tag{18}
\]

\[
R_d = a_0^d + a_1^d t^* + a_2^d RH^* + a_3^d t^* RH^*\tag{19}
\]

\[
\tau_d = a_0^\tau + a_1^\tau t^* + a_2^\tau RH^* + a_3^\tau t^* RH^*\tag{20}
\]

\[
U = a_0^u + a_1^u t^* + a_2^u RH^* + a_3^u t^* RH^*\tag{21}
\]

**Table 2. Matrix of full factorial design with two factors.**

<table>
<thead>
<tr>
<th>N</th>
<th>t</th>
<th>RH</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-1</td>
<td>-1</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>-1</td>
</tr>
<tr>
<td>3</td>
<td>-1</td>
<td>1</td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

Matrix of full Factorial of such a design with two (t and RH) factors is given in Table 1 developed with Software MODDE 5.0 (Umetrics AB, Umea, Sweden) allows creation and analyses experimental designs; the program assists the user for analysis of the results and prediction of the responses [9]-[11]. It calculates coefficients of the factors and allows modeling and optimization of the process. Obtained results according to matrix are presented in Table 1 were the response of impedance parameters is obtained from the experimental manufactured by [5]. Furthermore Fig.5 representing significant effect and interaction of the model parameters.

The mathematical model of the response (Cell voltage) is linear with significant interactions, given by:

\[
R_m = 0.00609 + 0.00171949t - 0.00250279RH\tag{22}
\]

\[
Q = 0.90425 - 0.148901t + 0.1275RH\tag{23}
\]

\[
R_p = 0.0118 + 0.00334376t + 0.000557375RH\tag{24}
\]

\[
R_d = 0.01245 + 0.00944438t + 0.0053026RH\tag{25}
\]

\[
\tau_d = 0.12025 + 0.0221923t - 0.0326524RH\tag{26}
\]

\[
U = 3.7225 - 0.450102t + 0.0459784RH\tag{27}
\]

**Evaluation of quality of the mathematical model**

The quality of the obtained mathematical model can be evaluated by two statistical criteria which are given directly by software MODDE 5.0 to check experimental (\( R^2 \) criterion) and predictive (\( Q^2 \) criterion) quality of the mathematical model. When values of \( R^2 \) and \( Q^2 \) are close to the unit, the model is considered as good and can be used for optimization and prediction [11]. As values of these two criteria, according to the model given by equation (15), are respectively \( R^2 = 0.999 \) and \( Q^2 = 0.943 \) the model can thus be used to predict and optimize the process.

**4. Simulation Results and discussion of the impedance response**

We simulate progressive behaviour of impedance with variation in time from (500 to 2700) under dehydrating conditions RH=10% (e.g., dry gas feeds). Bode plots of spectra from dehydrated PEMFCs are characterized by an increase of cell impedance magnitude across all frequencies and an increase (less capacitive) in phase angle in the mid to high frequencies fig(6). The dehydration effect is equally
visible in the Nyquist plot fig (7), which shows a right lateral shift by the amount of the membrane resistance \(R_{\text{int}}\) increase.

Under high load conditions, fuel cell current density increases and the production of water at the cathode by oxygen reduction reaction (2) and by electro-osmotic drag increases. Unchecked, this can lead to flooding case. The initial stage of flooding is characterized by a slow decrease in output voltage as liquid water begins to accumulate in the channels and constrict the gas flow thus increasing the diffusion related equivalent circuit parameters \(R_d\) and time constant \(\tau_d\).

We simulate progressive behaviour of impedance with variation in time from (500 to 2700) under flooding conditions RH=150%. Bode plots of spectra from flooding PEMFCs are characterized by an increase of low frequency cell impedance magnitude and a decrease in phase angle (more capacitive) in the mid to low frequencies fig(8).

Fig.6 Effect of dehydration on PEMFC: Bode plot (normal t=500sec → dehydrated t=2700 sec)
The flooding effect can be related to equivalent circuit parameter changes in the Nyquist plot Fig.9, which the absence of large variations in the high-frequency arcs. This behavior can be explained by noting that the humidification levels in the membrane (and consequently the membrane resistance) do not change between normal and flooded conditions (i.e., the membrane is fully humidified in both cases).

Fig. 7. Effect of dehydration on PEMFC: Nyquist plot (normal t=500 sec → dehydrated t=2700 sec)

Fig. 8. Effect of flooding on PEMFC: Bode plot (normal t=500 sec → flooded t=2700 sec)
Fig. 9. Effect of flooding on PEMFC: Nyquist plot (normal t=500sec→ flooded t=2700 sec).

In order to make a diagnostic of flooding and drying we simulate progressive behaviour of impedance with time (500 to 2700) and the relative humidity RH (%) from(10% to 100%) and Make a diagnosis-clogging a fuel cell using the 5 criteria behavior on the impedance

1-Internal resistors $R_{int}$ (measured at high frequency)
2-biasing resistors $R_{pol}$ (measured at low frequency)
3 frequency of arc-Summit $f_{max}$
4- Imaginary of arc summit $I_{max}$
5-area $(Re(Z)*Im(Z))$

As shown in Fig.10, the value of the resistance measured at high frequency of the stack $R_{int}$ increases with time acutely when RH% of cathode reactant gas decreases from 100% to 20%. The main reason is the conductivity of the membrane in a PEMFC is directly related to its water content. When RH% increases, the water content in membrane will increase, consequently the membrane conductivity will increase and the $R_{int}$ of the stack will decrease.

The resistance measured at low frequency of the stack $R_{pol}$ is shown in Fig 11, it gradually increases according to time as RH % of cathode reactant gas increases. Because the relative humidity (RH %) affect the proton mobility at high frequency.

Fig. 12 shows the frequency of arc –summit $f_{max}$ behavior. It emphasises the observation that the arc – summit frequency stays constant with variation of relative humidity RH % and times.

As shown in Fig. 13 and Fig 14, the value of imagery of arc summit $I_{max}$ and area$(Re(Z)*Im(Z))$ increases with time acutely when RH % of cathode reactant gas increases from 100% to 20%. The main reason is the conductivity of the membrane in a PEMFC is directly related to its water content. When RH increases, the water content in membrane will increase, consequently the membrane conductivity will increase and the $R_{int}$ of the stack will decrease.
consists in defining more systematic methods for identification of the parameters and their validation particularly in the time domain. Moreover, it would also be interesting to use the fuzzy logic FLC controller for water management based on resistance measured at high frequency of the stack $R_{int}$ and The resistance measured at low frequency of the stack $R_{pol}$.

References


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